

# Elasticity

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- **Elasticity**:- The property of a body, by virtue of which body regains its original size and shape when the applied force is removed, is known as **elasticity** and the body is known as **Elastic body**.

Eg. Spring, rubber, skin, etc.

- **Plasticity**:- The property of a body, by virtue of which body does not regain its original size and shape when the applied force is removed, is known as **plasticity** and the body is known as **Plastic body**.

Eg. Plastic paper, clay, putty, etc.

- **Rigidity**:- The property of a body, by virtue of which body does not change its original size and shape when the force is applied is known as **Rigidity**.

Eg. Wall, Black board, duster, etc.



**Stress:-** The restoring force per unit area is known as stress.

If **F** is the force applied and **A** is the area of cross section of the body.

$$\text{Stress} = F/A$$

The SI unit of stress is  $\text{N/m}^2$ .

**Strain:-** It is defined as change in dimensions per unit original dimensions.

Strain = change in dimensions/original dimensions

Strain has no unit.



There are 3 types of stress:-

1) Tensile or Longitudinal Stress:-

If the applied force produces change in length of a body, the stress associated is called as Tensile Stress.

$$\text{Longitudinal stress} = F/A = Mg/\pi r^2$$

2) Volume stress :-

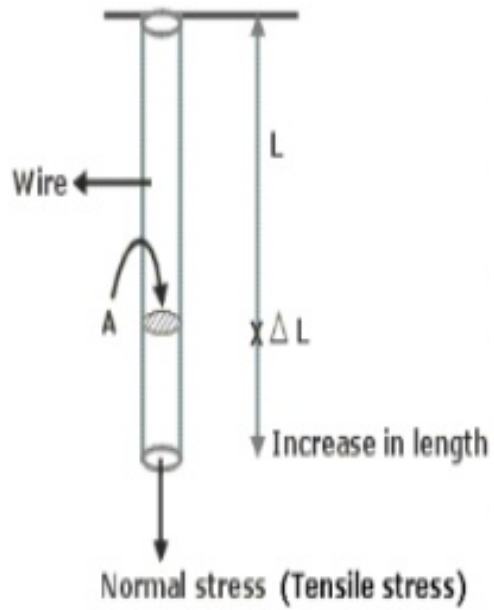
If the applied force produces change in volume of a body, the stress associated is called as Volume Stress.

$$\text{Volume Stress} = A \cdot dP/A = dP$$

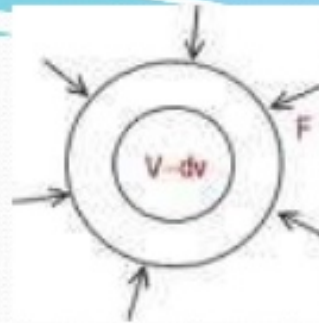
3) Shear stress :-

If the applied force produces change in shape of a body, the stress associated is called as Shear Stress.

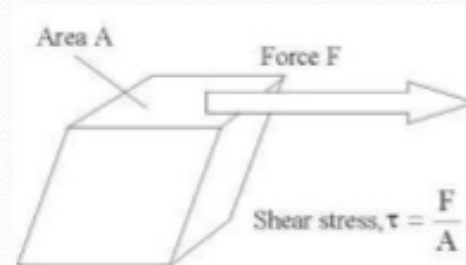
$$\text{Shear Stress} = \text{Tangential force} / \text{Area}$$



Longitudinal strain



Volume stress



Shear stress

There are 3 types of strain:-

1) Tensile or Longitudinal Strain:-

The change in the length per unit original length of the body is known as longitudinal strain.

$$\text{Longitudinal strain} = l/L$$

2) Volume stress :-

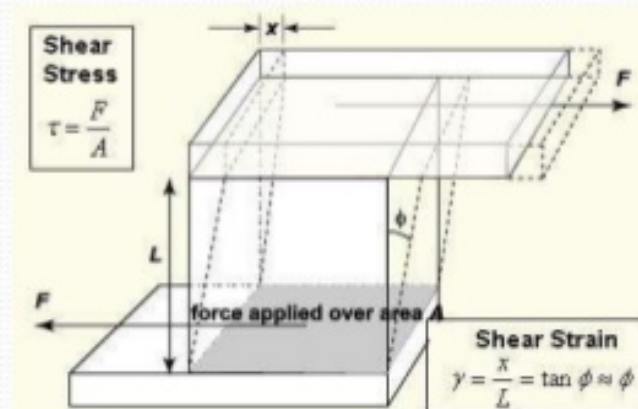
The change in the volume per unit original length of the body is known as volume strain.

$$\text{Volume Strain} = dV/V$$

3) Shear stress :-

The ratio of relative displacement of any layer to its perpendicular distance from fixed surface is known as shear strain.

$$\text{Shear Strain} = X/L$$





## HOOKE'S LAW:-

Statement:- *"Within elastic limit, stress is directly proportional to strain."*

Thus,

$$\text{stress} \propto \text{strain}$$

$$\text{stress} = M \times \text{strain}$$

where M = proportionality constant called as **modulus of elasticity**.

Therefore,  $M = \text{Stress}/\text{strain}$

There are 3 types of elastic constants:-

- 1) Young's Modulus (Y)
- 2) Bulk Modulus (K)
- 3) Modulus of Rigidity( $\eta$ )

### 1) Young's Modulus (Y):-

It is the ratio of longitudinal stress to the longitudinal strain.

$$\begin{aligned} Y &= \frac{\text{Longitudinal stress}}{\text{Longitudinal strain}} \\ &= \frac{(Mg/\pi r^2)}{(l/L)} \\ &= \frac{MgL}{\pi r^2 l} \end{aligned}$$

S.I unit of Y is  $\mathbf{N/m^2}$

Dimensions are  $[\mathbf{L^{-1} M^1 T^{-2}}]$

### 2) Bulk Modulus(K):-

It is the ratio of volume stress to the volume strain.

$$\begin{aligned} K &= \frac{\text{volume stress}}{\text{volume strain}} \\ &= \frac{dP}{(dV/V)} \\ &= \frac{V \cdot dP}{dV} \end{aligned}$$

S.I unit of Y is  $\mathbf{N/m^2}$

Dimensions are  $[\mathbf{L^{-1} M^1 T^{-2}}]$



### 3) Modulus of Rigidity( $\eta$ ):-

It is the ratio of shearing stress to the shearing strain.

$$\begin{aligned}\eta &= \text{shearing stress/shearing strain.} \\ &= (F/A)/\theta \\ &= F/A \theta\end{aligned}$$

### Poisson's Ratio( $\sigma$ ):

"It is defined as the ratio of lateral strain to the longitudinal strain."

$$\sigma = \text{lateral strain/longitudinal strain}$$

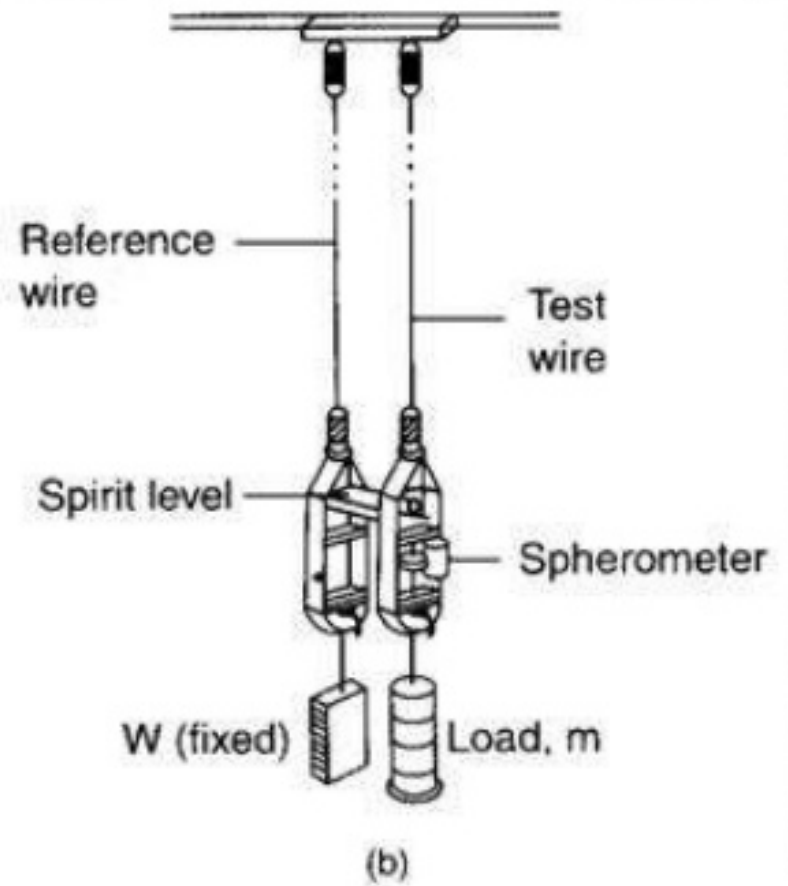
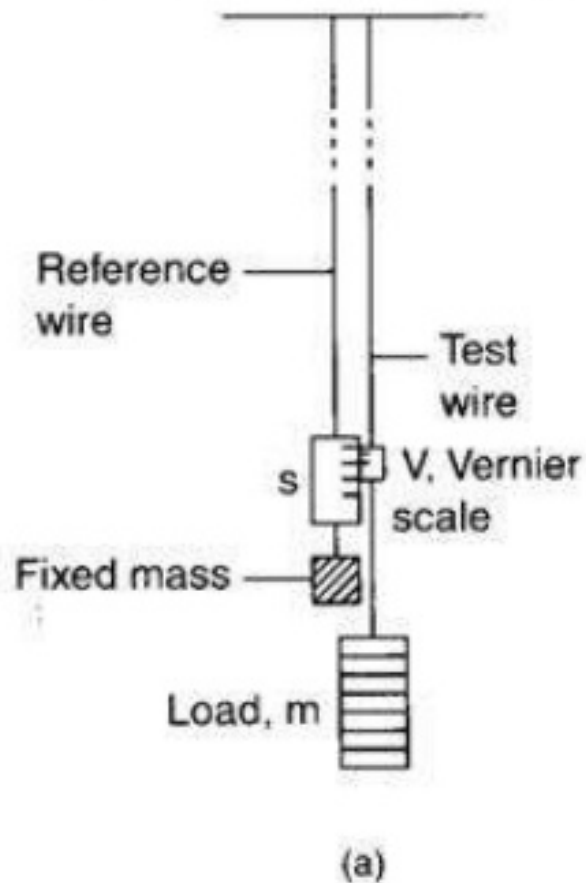
but, lateral strain = Change in dimension/original dimension

and longitudinal strain = Change in length/original length

$$\begin{aligned}\therefore \sigma &= \frac{(-dW/W)}{(l/L)} \\ &= \frac{dW.L}{Wl}\end{aligned}$$

Negative sign indicates that increase in length is accompanied by decrease in its transverse dimensions.

## Determination of Young's Modulus of the Material of a Wire



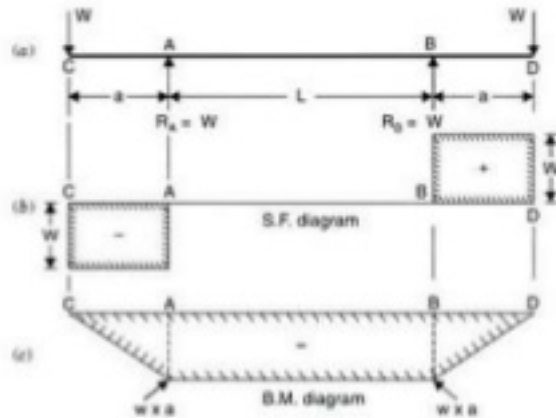
## 4.1 SIMPLE BENDING OR PURE BENDING

- When some external force acts on a beam, the shear force and bending moments are set up at all the sections of the beam
- Due to shear force and bending moment, the beam undergoes deformation. The material of the beam offers resistance to deformation
- Stresses introduced by bending moment are known as bending stresses
- Bending stresses are indirect normal stresses



## 4.1 SIMPLE BENDING OR PURE BENDING

- When a length of a beam is subjected to zero shear force and constant bending moment, then that length of beam is subjected to pure bending or simple bending.
- The stress set up in that length of the beam due to simple bending stresses



## 4.1 SIMPLE BENDING OR PURE BENDING

- Consider a simply supported beam with over hanging portions of equal lengths. Suppose the beam is subjected to equal loads of intensity  $W$  at either ends of the over hanging portion
- In the portion of beam of length  $l$ , the beam is subjected to constant bending moment of intensity  $w \times a$  and shear force in this portion is zero
- Hence the portion AB is said to be subjected to pure bending or simple bending

## 4.2 ASSUMPTIONS FOR THE THEORY OF PURE BENDING

- The material of the beam is isotropic and homogeneous. I.e. of same density and elastic properties throughout
- The beam is initially straight and unstressed and all the longitudinal filaments bend into a circular arc with a common centre of curvature
- The elastic limit is nowhere exceeded during the bending
- Young's modulus for the material is the same in tension and compression



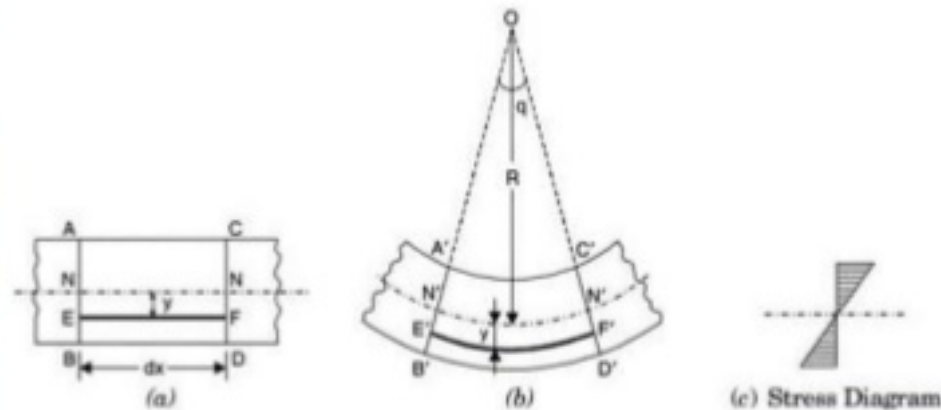
## 4.2 ASSUMPTIONS FOR THE THEORY OF PURE BENDING

- The transverse sections which were plane before bending remain plane after bending also
- Radius of curvature is large compared to the dimensions of the cross section of the beam
- There is no resultant force perpendicular to any cross section
- All the layers of the beam are free to elongate and contract, independently of the layer, above or below it.

## 4.4.1 STRAIN VARIATION ALONG THE DEPTH OF BEAM

- Consider a layer EF at a distance  $y$  from the neutral axis. After bending this layer will be deformed to E'F'.
- Strain developed =  $(E'F' - EF) / EF$

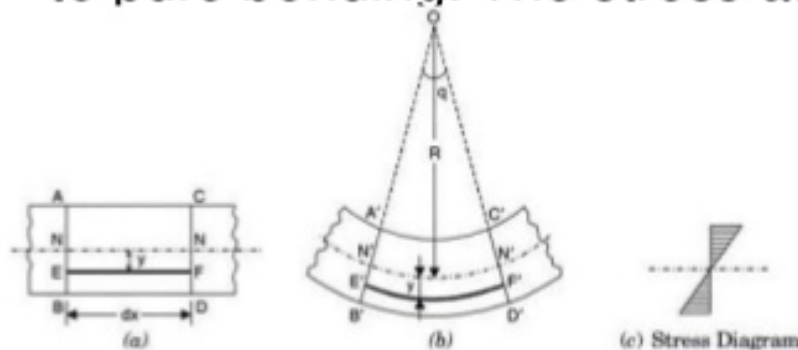
$$EF = NN = dx = R \times \theta$$



## 4.5 NEUTRAL AXIS

- For a beam subjected to a pure bending moment, the stresses generated on the neutral layer is zero.
- Neutral axis is the line of intersection of neutral layer with the transverse section
- Consider the cross section of a beam subjected to pure bending. The stress at a distance  $y$  from

$$=E/R$$



(c) Stress Diagram



## 4.7 CONDITION OF SIMPLE BENDING & FLEXURAL RIGIDITY

- Bending equation is applicable to a beam subjected to pure/simple bending. I.e. the bending moment acting on the beam is constant and the shear stress is zero
- However in practical applications, the bending moment varies from section to section and the shear force is not zero
- But in the section where bending moment is maximum, shear force (derivative of bending moment) is zero
- Hence the bending equation is valid for the section where bending moment is maximum

## 4.7 CONDITION OF SIMPLE BENDING & FLEXURAL RIGIDITY

- Or in other words, the condition of simple bending may be satisfied at a section where bending moment is maximum.
- Therefore beams and structures are designed using bending equation considering the section of maximum bending moment
- Flexural rigidity/Flexural resistance of a beam:-
- For pure bending of uniform sections, beam will deflect into circular arcs and for this reason the term circular bending is often used.



